

INSTALLATION AND COMMISSIONING GUIDE



CAN bus-based I/O module, CIO 308 8 multi-inputs

MountingTerminals and wiringCommissioning, using the utility software



DEIF A/S · Frisenborgvej 33 · DK-7800 Skive Tel.: +45 9614 9614 · Fax: +45 9614 9615 info@deif.com · www.deif.com

1. Introduction

| 1.1 Warnings, legal information and safety | 3 |
|--|-----|
| 1.1.1 Warnings and notes | . 3 |
| 1.1.2 Legal information and disclaimer | 3 |
| 1.1.3 Safety issues | 3 |
| 1.2 About the installation and commissioning guide | .4 |
| 1.2.1 General purpose | 4 |
| 1.2.2 Intended users | 4 |
| 1.2.3 Contents and overall structure | 4 |

2. Installation, mounting and wiring

| 2.1 Installation | 5 |
|---------------------------------|----|
| 2.2 Mounting | 5 |
| 2.2.1 Mounting the CIO modules | 5 |
| 2.2.2 Dimensions | 5 |
| 2.3 Common functions | 6 |
| 2.4 Wiring and terminals | 8 |
| 2.4.1 Terminal overview CIO 308 | 8 |
| 2.4.2 CIO 308 wiring | 11 |
| 2.4.3 CAN bus | 11 |

3. Communication

| 3.1 | Communication setup | 14 |
|-----|---|----|
| | 3.1.1 Step-by-step guide to setting up communication the first time | 15 |
| | 3.1.2 Step-by-step guide to update firmware to CIO module | 15 |

4. I/O setup

| 4.1 CIO info tab | .16 |
|---|------|
| 4.2 Status relay | .16 |
| 4.3 Multi-input | 18 |
| 4.3.1 Setting up a multi-input | . 18 |
| 4.3.2 Thermocoupler with cold junction compensation | .20 |
| 4.3.3 Wire fail detection | .21 |
| 4.3.4 Change text in the display | 23 |

1. Introduction

1.1 Warnings, legal information and safety

1.1.1 Warnings and notes

Throughout this document, a number of warnings and notes with helpful user information will be presented. To ensure that these are noticed, they will be highlighted as follows in order to separate them from the general text.

Warnings



DANGER!

This highlights dangerous situations. If the guidelines are not followed, these situations could result in death, serious personal injury, and equipment damage or destruction.



CAUTION

INFO

This highlights potentially dangerous situations. If the guidelines are not followed, these situations could result in personal injury or damaged equipment.

Notes



Notes provide general information, which will be helpful for the reader to bear in mind.

1.1.2 Legal information and disclaimer

DEIF takes no responsibility for installation or operation of the generator set. If there is any doubt about how to install or operate the engine/generator etc. controlled by the specific extension, the company responsible for the installation or the operation of the extension must be contacted.



DANGER!

The CIO module is not to be opened by unauthorised personnel. If opened anyway, the warranty will be lost.

Disclaimer

DEIF A/S reserves the right to change any of the contents of this document without prior notice.

The English version of this document always contains the most recent and up-to-date information about the product. DEIF does not take responsibility for the accuracy of translations, and translations might not be updated at the same time as the English document. If there is a discrepancy, the English version prevails.

1.1.3 Safety issues

Installing and operating the CIO module may imply work with dangerous currents and voltages. Therefore, the installation should only be carried out by authorised personnel who understand the risks involved in working with live electrical equipment.

DANGER!

Be aware of the hazardous live currents and voltages. Do not touch any live inputs as this could lead to injury or death.

1.2 About the installation and commissioning guide

1.2.1 General purpose

This installation and commissioning guide mainly includes general product and hardware information, mounting instructions, terminal strip descriptions, I/O lists and limits, wiring descriptions and how to produce translations for the CIO module through the USW.

The general purpose of this document is to give the user important information to be used in the installation of the unit.



DANGER!

Please make sure to read this document before starting to work with the CIO module and the controller. Failure to do this could result in human injury or damage to the equipment.

1.2.2 Intended users

This installation and commissioning guide is mainly intended for the person responsible for the design and installation. In most cases, this would be a panel builder designer. Naturally, other users might also find useful information in the document.

1.2.3 Contents and overall structure

This document is divided into chapters, and in order to make the structure simple and easy to use, each chapter will begin from the top of a new page.

2.1 Installation

Installation

The CIO module is delivered in a sturdy carton to prevent shipping damage. When you receive a system, check the part number against that of the requisition and packaging list for agreement. Inspect for damage, and if there is evidence of such, immediately file a claim with the carrier and notify the regional DEIF sales office, your sales representative or a sales representative at DEIF's head office in Skive, Denmark.

If the unit is not installed immediately, store it in the original shipping package in a moisture and dust free environment.

2.2 Mounting

2.2.1 Mounting the CIO modules

The CIO module is designed for mounting in a closed cabinet on a DIN rail. The module can be mounted on either a TS35 or G-type rail. The unit must be mounted where the ambient temperature does not exceed the range -40 to +70 °C.

2.2.2 Dimensions

The CIO 308 module dimensions are presented here in mm (inches):



2.3 Common functions



1. LED1 (Status LED)

LED1 indicates the operation status of the module, and the status output of this LED is located at terminal 3-4.

Set up as either status or configurable relay:

Set up as status relay

| LED colour | Description |
|--------------|---|
| Green | Status is OK, the relay is closed. |
| Red constant | The CIO module is not working correctly, the relay is open. |
| Red flashing | ID 0 is selected, relay is open. |

Set up as configurable relay

| LED colour | Description |
|---------------------|---|
| Green | Status is OK, the relay is closed. |
| Turned off/no light | Status is OK, the relay is open. |
| Red constant | The CIO module is not working correctly, the relay is open. |
| Red flashing | ID 0 is selected, relay is open. |
| Yellow | The relay is closed, status is not OK. |

2. Terminal resistor

The CIO module has a built-in 120 ohm end-termination for the CAN bus line which can be activated via the switch (S1) located at terminal 5. See the section "CAN bus" in "Wiring and terminals" for more information and to see when to activate the switch.

3. LED2 (CAN bus LED)

LED2 indicates the status of the CAN bus communication to the host controller. This LED is located at terminal 7.

| LED colour | Description |
|----------------|---|
| Green constant | Communication to the controller is working correctly. |
| Red constant | No CAN bus communication detected. |
| Red 2 flashes | CAN bus communication detected, but no CIO-specific communication |
| Red flashing | CIO communication detected, but not to this module. |

4. ID selector

The ID selector is used to give CIO modules of the same type different IDs.

CIO 116 can use IDs from 1 to 15

- CIO 208 can use IDs from 1 to 15
- CIO 308 can use IDs from 1 to 15

5. USB for firmware update

The firmware of the CIO modules can be updated via the USB port.

2.4 Wiring and terminals

2.4.1 Terminal overview CIO 308



| Terminal | Name | Description | Comment | |
|----------|--------|---------------|------------------------------|--|
| 1 | + | +12/24 V DC | Power supply | |
| 2 | - | 0 V DC | | |
| 3 | Statua | Common | Status output (configurable) | |
| 4 | Status | Normally open | Status output (configurable) | |
| 5 | Н | CAN-High | | |
| 6 | Com | CAN-Common | CAN bus interface | |
| 7 | L | CAN-Low | | |
| | | | | |

| Terminal | Name | Description | Comment | |
|----------|------|-------------|----------------|---------------------|
| 8 | | Input A | | |
| 9 | 18 | Input B | Multi-input 8 | |
| 10 | | Input C | | |
| 11 | | Input A | | |
| 12 | l11 | Input B | Multi-input 11 | |
| 13 | | Input C | | |
| 14 | | Input A | | Multi-input group 1 |
| 15 | 114 | Input B | Multi-input 14 | |
| 16 | | Input C | | |
| 17 | | Input A | | |
| 18 | 117 | Input B | Multi-input 17 | |
| 19 | | Input C | | |
| | | | | |
| 20 | | Input A | | |
| 21 | 120 | Input B | Multi-input 20 | |
| 22 | | Input C | | |
| 23 | | Input A | | |
| 24 | 123 | Input B | Multi-input 23 | |
| 25 | | Input C | | |
| 26 | | Input A | | Multi-input group 2 |
| 27 | 126 | Input B | Multi-input 26 | |
| 28 | | Input C | | |
| 29 | | Input A | | |
| 30 | 129 | Input B | Multi-input 29 | |
| 31 | | Input C | | |

Input LED

Each multi-input has its own LED, and the table below illustrates when the LED is on/off.

| Input type | LED | Description |
|---------------|-----|--|
| Digital input | On | Input is active |
| | Off | Input is inactive |
| | On | Within input range 4 to 20 mA |
| 0(4) to 20 mA | Off | Outside input range 4 to 20 mA (LED is flashing when in protection mode: >30 mA) |
| 0 to 10 V | On | Within input range 0.2 to 10 V |
| | Off | Outside input range 0.2 to 10 V |
| DMI | On | Within input range 10 to 2500 $\boldsymbol{\Omega}$ |
| | Off | Outside input range 10 to 2500 $\boldsymbol{\Omega}$ |

| Input type | LED | Description |
|---------------|-----|--|
| Pt100 sensor | On | Within selected input range (Low range -50 to 250°C or high range: -200 to 850°C) |
| | Off | Outside selected input range (Low range -50 to 250°C or high range: -200 to 850°C) |
| Pt1000 sensor | On | Within selected input range (Low range -50 to 250°C or high range: -200 to 850°C) |
| | Off | Outside selected input range (Low range -50 to 250°C or high range: -200 to 850°C) |
| Thermocouple | On | Within input range of selected type of thermocouple |
| memocoupie | Off | Outside input range of selected type of thermocouple |

2.4.2 CIO 308 wiring



INFO

When thermocouples and Pt100/ Pt1000 sensors are used, it is recommended to connect one of the C terminals to Earth (all C terminals are internally connected). It will minimise noise and sensitivity if touching terminals when measuring.

INFO

Twisted pair or/and shielded cable on input, is recommended to achieve specified accuracy and for optimisation of immunity-noice.

2.4.3 CAN bus

The CIO module(s) can be configured as the only device on the CAN bus or together with an engine controller (ECU) on the same CAN bus as shown in the below example. CIO module(s) can be placed together with all the different engine protocols which are available in the AGC (both J1939 and CANopen), because the CIO module will adapt to the baud rate on the CANline.

It is possible to connect up to three CIO modules of each type to one AGC.

Below is an example that shows how the CAN bus can be connected:



AGC 200

On the AGC 200, only CAN port C is available.

| Terminal | Function | Description |
|----------|----------|-------------|
| 13 | CAN H | |
| 14 | Com | CAN port C |
| 15 | CAN L | |

AGC-4/AGC Plant Management

On the AGC-4 and AGC Plant Management, it is possible to use the CAN ports C, D, E or F, and you need to have at least one of the following options: H5, H8 or H12.



INFO Option H7 is not available for use with CIO modules.

| Terminal | Function | Description |
|----------|----------|-------------|
| 29 | CAN H | |
| 30 | Com | CAN port C |
| 31 | CAN L | |
| | | |
| 32 | CAN H | |
| 33 | Com | CAN port D |
| 34 | CAN L | |
| | | |
| 131 | CAN L | |
| 132 | Com | CAN port E |
| 133 | CAN H | |
| | | |

| Terminal | Function | Description |
|----------|----------|-------------|
| 128 | CAN L | |
| 129 | Com | CAN port F |
| 130 | CAN H | |

3. Communication

3.1 Communication setup

A few parameters revolving around communication to the CIO can be accessed through the display. Through the CIO tab in the USW, full access to all the CIO parameters is available. The CIO configuration menu is accessed from the top menu bar of the USW.

| | Ø DEIF utility softw | vare - 3.41. | | onnected | to "AGC 252" (versi | on 9.91.0 rev. 1 | 13067 | | | 6 | | |
|----------|----------------------|-----------------|--|------------|------------------------------------|------------------|---------|-----------------------|------------------|-------------|---|------|
| | File Connection | Param | eters Help | | | | | | | | | |
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| | Dep | DG a | C O configuratio S S | n | | | | | | | - | × |
| | 4 | DG c | Device list | | | | 0 | ommunication settings | for all CIO modu | les | | |
| | | DG r | Communication | Comm | | | | | | | | |
| • | Deutice | | CIO 116 no. 1 | Comm | • | | | | | | | |
| 0 | CA. | | CIO 116 no. 2 CIO 116 no. 3 CIO 208 no. 1 CIO 208 no. 2 CIO 208 no. 2 CIO 208 no. 2 | | CAN bus setup CIO communication | [7890] | Enabled | _ | | | | |
| 9 | Application | | CIO 308 no. 2 | | CIO communication | port [7840] | | | | | | |
| | | Ē | CIO 308 no. 3 🥥 | - | Amount of CIO module | es | CAN C | _ | | | | |
| | Alarms | SELE | | | Amount of CIO 116 | modules | 3 | \sim | ſ | 1 | | |
| 6 | | | | | Amount of CIO 208 | modules | 3 | ~ | | Auto detect | | |
| v | | A) (D) | | | | | - | - | | CIO modules | | |
| | Trending | AVR | | | Amount of CIO 308 | modules | 3 | ~ | L | | | |
| | | 100 | | | | | | | | | | |
| | < <u>_</u> | E | | | Iodule name | A Module | ND. | CIO missing fail | daee | Delay (sec) | | |
| | , second | = | | c | IO 116 no. 1 | 1 | 10 | Shutdown | (0035 | D.0 | | |
| 0 | Parameters | •== | | c | IO 116 no. 2 | 2 | | Trip GB | (| D.O | | |
| 0 | +++ | | | c | IO 116 no. 3 | 3 | | Warning | 0 | D.O | | |
| | ann. | 0% | | С | IO 208 no. 1 | 1 | | Safety stop | C | D.O | | |
| | TTT | | | C | IO 208 no. 2 | 2 | | Warning | 0 | D.O | | |
| | inputs/Outputs | 📕 2 a | | C | IO 208 no. 3 | 3 | | Warning | 0 | D.O | | |
| | = | | | С | IO 308 no. 1 | 1 | | Warning | 0 | 0.0 | | |
| | <mark>8-</mark> | | | C | IO 308 no. 2 | 2 | | Warning | 0 | 0.0 | | |
| | Options | | | C | IO 308 no. 3 | 3 | | Warning | | 0.0 | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |

1. CIO configuration menu

When you open the CIO configuration menu, the first page is Communication setup.

2. Read configuration from the controller

3. Write configuration to the controller

4. CAN bus setup

The CAN port for the CIO modules is illustrated as well as the communication port, which are both configured in the USW parameter list.

5. Auto detect

If the CIO modules are already connected and have the correct ID, the USW can automatically detect the number and composition of CIO modules by using the auto detect function.

6. Device navigation list

Click a module from the list to access setup of the module. The green/grey light indicates if connection to the module is established.

7. Manually select how many devices are connected

8. List of modules

INFO

The module ID must correspond with the ID selected on the module and can be changed manually in the list. The fail class and delay set here are triggered if the specific module is missing.



The first time you open the menu, the buttons will be inactive and it is necessary to read the configuration from the controller.



If the communication to a CIO 116 or CIO 308 module is lost, the AGC will continue with the last received input value.

3.1.1 Step-by-step guide to setting up communication the first time

Follow these steps to establish communication to the CIO modules. Setup of the I/Os is described in a later chapter.

- · Adjust the ID from 1-15 on the switch by rotating the screw in the lower left corner
- · Select which CAN port to use for CIO (parameter 7840).

Select "Ext. modules DEIF" if the CAN port is only used to CIO modules, but If an engine (ECU) also is connected to the CAN line then "H5 EIC" or similar should be selected.

- Enable CIO communication (parameter 7890).
- Open the CIO menu by pressing the CIO icon
- · Read the configuration from the controller.
- · Auto-detect the number of modules and their ID.

This only works if the CIO modules are connected, but it is also possible to manually add and configure modules by changing value in "Amount of CIO xxx modules"

- · Determine fail class for module missing for all modules.
- Write the configuration to the controller.



CAUTION

When the configuration is written to the controller all I/Os are temporarily disabled. For example, all relays are deenergised.

3.1.2 Step-by-step guide to update firmware to CIO module

Follow these steps to update the firmware for a CIO module.

- · Apply power to the module
- Set ID to 0.
- · Connect a USB cable between the CIO module and a PC
- · Open the utility software and connect to the CIO module via USB.
- Login as "Customer" with the password 2000.
- Write a new firmware to the device by pressing this icon ²
- When the firmware is completed, the connection can be stopped 🔅, the USB cable can be removed, and the ID should be returned to the desired ID.

4.1 CIO info tab

| CIO configuration Solution | | × |
|---|---|---|
| Device list | Communication settings for CTO 308 module | |
| Communication | | |
| CIO 116 no. 1 CIO 116 no. 2 CIO 116 no. 3 CIO 208 no. 1 CIO 208 no. 2 CIO 208 no. 3 CIO 308 no. 2 CIO 308 no. 2 CIO 308 no. 3 | Module ID 1 Software version 9902 Software revision 762 Hardware version 10 | ~ |
| | 68.0 Input 8 | |
| | 38.5 Input 11 | |
| | 850.0 Input 14 | |
| | 39.9 Input 17 | |
| | 0.00 Input 20 | |
| | 0.00 Input 25 | |
| | 0.06 Input 29 | |
| | ٢ | > |

1. Module info

This section gives an overview of the specific module's ID and the software and hardware version of the module. This information is important if support is needed for the product.

2. Communication test

When you click the Communication test button, the CAN bus LED (LED2) of the corresponding module will flash green.

3. I/O status

In this section, the value (like temperature, pressure, voltage and so on) is shown for each input.

4.2 Status relay

The module has a status relay, which can be used as a status relay or as a configurable relay.

INFO

Power cycling the CIO module while there is no communication to the AGC will reset the settings results, and the relay will be set as a status relay until communication is established. The CIO configuration is stored in the AGC, and this means that the CIO module will be configured when the communication to the AGC is available.

| 0 | | CIO configuration _ 🗆 × | | | | | | | | | | | | | | |
|--|-----------------------|---|--------|---------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 🖬 🔅 🎲 | | | | | | | | | | | | | | | | |
| Device list | | Communication settings for CIO 116 module | | | | | | | | | | | | | | |
| Communication | CIO info Status relay | I10 | I11 | I12 I13 | I14 | I15 | I16 | I17 | I19 | I20 | I21 | I22 | I23 | I24 | I25 | I26 |
| CIO 116 no. 2 CIO 116 no. 2 CIO 116 no. 3 CIO 208 no. 1 | Relay type | | Status | s relay 🗸 🗸 🗸 |] | | | | | | | | | | | |
| CTO 208 no. 2 | CAN bus failure set o | utput | Low | ~ | | | | | | | | | | | | |
| | Relay function | | Alarm | relay ND 🗸 🗸 | | | | | | | | | | | | |
| | Delay | | 5 | Sec | | | | | | | | | | | | |
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1. Relay type

This setting has two states: Status relay and Configurable.

If it is used as a status relay, the relay will stay closed as long as the state of the module is OK, which corresponds with a constant green status LED (see Status LED). If the relay is used as a status relay, the settings below are disregarded.

2. CAN bus failure set output

This setting has three levels: Low, High and Stay. In case of a CAN bus failure, the related relay will change its state based on this setting. If it is set to Stay, the relay will keep its current state until communication is working again.

3. Relay function

The relay function can be set to five different settings:

Alarm relay ND

The related relay is used as an alarm relay of the type "ND" (Normally De-energised).

The relay is activated until the alarm that caused the activation is acknowledged and gone.

Limit relay

The relay will activate at a certain predefined limit set point. When the condition that activated the relay has returned to normal, and when the delay has expired, the relay will deactivate. The delay is adjustable.

An output relay should be configured as a limit relay, otherwise an alarm will be raised when the output is activated.



To use the relay in M-Logic, it must be configured as a limit relay.

Horn relay

All configurable relays can be selected to be a horn output (horn relay).

This means that, for example, the relay can be connected to an alarm annunciator, like a horn. When "Horn relay" is selected, an external horn is activated every time a new alarm occurs. If the alarm horn timer in parameter 6130 is adjusted to 0 seconds, the horn remains activated until the alarm is acknowledged. If the alarm horn parameter (6130) is not 0 seconds, the horn relay output is active until the timer expires and then the relay deactivates, even though the alarm is still present.

Siren relay

When "Siren relay" is selected, an external siren is activated on all alarms, like the selection "Horn relay". When the siren relay is activated and another alarm is active, a short-time reset will be activated. If the alarm horn timer in parameter 6130 is adjusted to 0 seconds, the siren relay remains activated until all alarms are acknowledged.

Alarm relay NE

The related relay is used as an alarm relay of the type "NE" (Normally Energised).

The relay is normally closed, and if the related alarm occurs, the relay will open until the alarm is acknowledged and gone.

4. Delay

Used when the relay function is "Limit".

The delay setting indicates how many seconds the relay stays energised after the input has become inactive. This functionality is also called off-delay.

4.3 Multi-input

4.3.1 Setting up a multi-input

Below is the functionality generally described. The screen changes depending on the input type (item 1 on the picture).



1. Input type

This setting determines the type of signal that the sensor sends to the input. Among the options are: Pt100, Pt1000, 0-10 V, RMI, 0-20 mA, thermocoupler types and binary.

2. Scaling

This list contains options regarding the origin of the multi-inputs measurement. It is possible to select between various units like °C, bar, kW and "No unit". There is also a scaling involved, which can be 1/1, 1/10 and 1/100.

If 1/100 is selected, there are 2 decimals in the output value, the max value is 327.67, and there are 0 decimals if 1/1 is chosen, then the max value is 32767.

3. Selected curve

This graph shows the curve for the values in the Configurable Curve table (item 4).

4. Configurable curve

In this table it is possible to type the relation between input 0-10 V and output kW 1/10 in this example.

As seen in the table, the input ranges from 0-5 V, and the output is 0.0-1.0 kW. If the input voltage goes above 5 V, the output will stay at 1.0 kW.

5. Wire-break detection

If the input signal is outside of configured range, the wire fail detection is activated. It depends on the input type working area of the sensor whether open circuit and short circuit failures will be detected. Read more about this in the chapter about wire fail detection.

6. Alarm setup

It is possible to set two alarms, and the related settings are the same as for regular inputs on the AGCs. The selected set point relates to the output value. In this example, the output value is 0-1 kW, and the first alarm activates when the value has been above 0.7 kW in 1 second.

4.3.2 Thermocoupler with cold junction compensation

The CIO 308 module compensates for the cold junction. This can be done with the internal temperature measurement if the thermocoupler is connected to the CIO 308 module terminals.

If there is a long distance to the measured object, a conductor is often used from the CIO module to a junction box, where the thermocoupler is connected. In this case, it is possible to compensate by using a temperature sensor, for example a Pt100, and place it in the junction box as the picture below illustrates:



Configuring the cold junction function in the CIO 308 module through the USW:

| | 1 | | | | _ | |
|--|--|--|-----------------------------|-----------------------|---|--|
| Device list | | Communica | tion settings for CIO 308 m | odule | | |
| Immunication 116 no. 1 116 no. 2 116 no. 3 1000 no. 1 1000 no. 1 1000 no. 1 1000 no. 2 1000 no. 1 1000 no. 2 1000 no. 2 1000 no. 2 | CIO info Status relay I8 Input type Cold Junction Compensation | I11 I14 I17 I20 TC type J ∨ CIO 308-1.11 ∨ | 123 I26 I29 | | | |
| 308 no. 3 🥥 | | | <u>1st Alarm</u> | Disabled V | | |
| | | | Alarm when input is | High \checkmark | | |
| | | | Set point | 100.0 | | |
| | | | Delay | 1.0 🔹 Sec. | | |
| | | | Fail class | Warning \checkmark | | |
| | | | Output A | Not used \checkmark | | |
| | | | Output B | Not used \sim | | |
| | | | Auto aknowledge | Disabled \checkmark | | |
| | | | Inhibits | Inhibits V | | |
| | | | 2nd Alarm | Disabled \lor | | |
| | | | Alarm when input is | High \checkmark | | |
| | | | Set point | 0.8 | | |
| | | | Delay | 10.0 Sec. | | |
| | | | Fail class | Warning \checkmark | | |
| | | | Output A | Not used \checkmark | | |
| | | | Output B | Not used \sim | | |
| | | | Auto aknowledge | Disabled \checkmark | | |
| | | | Inhibits | Inhibits ∨ | | |
| | | | | | | |
| | | | | | | |

1. Input type

Here you can select the thermocoupler and which type it is.

2. Cold Junction Compensation

This is where the compensation input is selected. It is possible to choose another input that should be used for cold junction compensation, or the internal temperature in the CIO 308 module can be selected.

4.3.3 Wire fail detection

The CIO 308 module can detect wire fail if the signal goes outside the working range. It depends on the signal type and working range if a short circuit or a broken cable will be detected.

To prevent a false "Wire fail" alarm, small deviations from the working area are accepted for some signals.

| Table 4.1 | Wire break values | overview |
|-----------|-------------------|----------|
| | | |

| Input | Wire failure low area | Normal range | Wire failure high area |
|---------------------------|--|--------------|---|
| 0-10 V | 1 V below lowest value in the working range | Configurable | 1 V above highest value in the working range |
| 0-20 mA | 1 mA below lowest value in the working range | Configurable | 1 mA above highest value in the working range |
| Thermocoupler (all types) | Does not have wire fail detection | 1 | |

| Input | Wire failure low area | Normal range | Wire failure high area |
|---------------------|--|--------------|--|
| Pt100 (low range) | < 80.3 Ω | 80.3-194.1 Ω | > 194.1 Ω |
| Pt100 (high range) | < 18.5 Ω | 18.5-390.5 Ω | > 390.5 Ω |
| Pt1000 (low range) | < 803 Ω | 803-1941 Ω | > 1941 Ω |
| Pt1000 (high range) | < 185 Ω | 185-3905 Ω | > 3905 Ω |
| RMI (all types) | 10 % of the range below the lowest value | Configurable | 10 % of the range above the highest value |
| Binary | Short circuit cannot be detected | - | Set a 240 Ω resistor parallel with the switch (see picture below) |

Examples:

0-10 V

If the signal is configured to 2-10 V, "Wire fail" alarm will occur if the voltage is below 1 V or above 11 V. If the signal is configured to 0-10 V, a wire break cannot be detected because the signal would become 0 V in case of a wire break.

0-20 mA

If a 0-20 mA signal is used, it is not possible to detect wire break, because in this case the signal would become 0 mA, which is inside the acceptable area. A 4-20 mA could be used instead to detect wire break. In this case, a wire break would be detected below 3 mA and above 21 mA.

RMI

If an RMI signal is used where the working area is 50-200 Ω , then the tolerance is 15 Ω (10 % of the range, 150 Ω), so the "Wire fail" alarm occurs below 35 Ω or above 215 Ω .

Binary

To detect wire failures, a 240 Ω resistor must be put in parallel to the switch, but if wire fail detection is not used, then it is not necessary to use the resistor. If used, the resistor should always be located near the switch. When ~0 Ω is measured, the terminal is energised, and when 240 ohm is measured, the terminal is deenergised. If a high resistance is measured, then the "Wire fail" alarm is triggered and "N.A." is shown as a value in the display. See the picture below for a wiring example of a binary input with wire break detection.



4.3.4 Change text in the display

In the "Translations" section in the utility software, it is possible to change the text shown in the display. This can be used to translate the text into another language and to change the text to something more informative regarding what is measured. For AGC-4 and AGC PM, it is also possible to change the unit to the measurement.

There are numerous languages, and the language is set in parameter 6080.

AGC-4 and AGC PM

For the input where the text should be customised, the scaling has to be set to "No unit 1/100", "No unit 1/10" or "No unit 1/1". In the translations section, there are 3 texts to each input, where the text with 2 decimals relates to "No unit 1/100" and so forth. As the picture below illustrates, it is also possible to configure the "CIO - X.XX N.A." if needed.

As example, "CIO-1.17 ###.##" would relate to CIO 308 module no. 1 input 17 with scaling "No unit 1/100" and could be changed into "Fuel tank ###.## L". The hash symbol (#) represents the digits from the measurement.

| | AAa 🏦 | i 🗸 X | | | |
|--------------|--------|---------------------|---------------------|------------------|------------------|
| | | Master | | | |
| | Status | Master language 🛛 🗠 | / Language 1 | / Language 2 | / Language 3 |
| <u>₀_h</u> ▲ | | CIO-1.17 N.A. | CIO-1.17 N.A. | CIO-1.17 N.A. | CIO-1.17 N.A. |
| 0 <u>-</u> | | CIO-1.17 ###### | CIO-1.17 ###### | CIO-1.17 ###### | CIO-1.17 ###### |
| <u> </u> | | CIO-1.17 #####.# | CIO-1.17 #####.# | CIO-1.17 #####.# | CIO-1.17 #####.# |
| Options | | CIO-1.17 ####.## | Fuel Tank ####.## L | CIO-1.17 ####.## | CIO-1.17 ####.## |
| ⇔ ⊫] | | CIO-1.20 N.A. | CIO-1.20 N.A. | CIO-1.20 N.A. | CIO-1.20 N.A. |
| | | CIO-1.20 ###### | CIO-1.20 ###### | CIO-1.20 ###### | CIO-1.20 ###### |
| Logs | | CIO-1.20 #####.# | CIO-1.20 #####.# | CIO-1.20 #####.# | CIO-1.20 #####.# |
| | | CIO-1.20 ####.## | CIO-1.20 ####.## | CIO-1.20 ####.## | CIO-1.20 ####.## |
| e 🦻 | | CIO-1.23 N.A. | CIO-1.23 N.A. | CIO-1.23 N.A. | CIO-1.23 N.A. |
| | | CIO-1.23 ###### | CIO-1.23 ###### | CIO-1.23 ###### | CIO-1.23 ###### |
| Translations | | CIO-1.23 #####.# | CIO-1.23 #####.# | CIO-1.23 #####.# | CIO-1.23 #####.# |
| ••••• | | CIO-1.23 ####.## | CIO-1.23 ####.## | CIO-1.23 ####.## | CIO-1.23 ####.## |

AGC 200

The displayed text can be edited in the translations section, and an example of this is shown in the picture below. The unit of the measurement can also be changed in the translation setting, but the text field for the units are shared among all text fields. This means that if "%" is changed to "m3", then m3 will be used at all places where the unit was % originally.

| | AA a | #1 - 12 | 8 | | | | |
|---------------|-------------|----------------|---------------------|---------------------|--------------|--------------|--------------|
| (DEIF) | | | Master | | | | |
| | Statu | JS | Master language 🛛 🗠 | / Language 1 | / Language 2 | / Language 3 | / Language 4 |
| · • | \bigcirc | Translated | CIO 308 1.11 | Winding temp. | CIO 308 1.11 | CIO 308 1.11 | CIO 308 1.11 |
| | \bigcirc | Translated | CIO 308 1.14 | Air inlet temp. | CIO 308 1.14 | CIO 308 1.14 | CIO 308 1.14 |
| = | \bigcirc | Translated | CIO 308 1.17 | Fuel level | CIO 308 1.17 | CIO 308 1.17 | CIO 308 1.17 |
| Logs | \bigcirc | Translated | CIO 308 1.20 | Cooling water temp. | CIO 308 1.20 | CIO 308 1.20 | CIO 308 1.20 |
| øé ∖ _ | \bigcirc | Translated | CIO 308 1.23 | CIO 308 1.23 | CIO 308 1.23 | CIO 308 1.23 | CIO 308 1.23 |
| | \bigcirc | Translated | CIO 308 1.26 | CIO 308 1.26 | CIO 308 1.26 | CIO 308 1.26 | CIO 308 1.26 |
| Translations | \bigcirc | Translated | CIO 308 1.29 | CIO 308 1.29 | CIO 308 1.29 | CIO 308 1.29 | CIO 308 1.29 |
| ····• | \bigcirc | Translated | CIO 308 1.8 | CIO 308 1.8 | CIO 308 1.8 | CIO 308 1.8 | CIO 308 1.8 |
| | \bigcirc | Translated | CIO 308 2.11 | CIO 308 2.11 | CIO 308 2.11 | CIO 308 2.11 | CIO 308 2.11 |
| OR | \bigcirc | Translated | CIO 308 2.14 | CIO 308 2.14 | CIO 308 2.14 | CIO 308 2.14 | CIO 308 2.14 |
| M-Logic | \bigcirc | Translated | CIO 308 2.17 | CIO 308 2.17 | CIO 308 2.17 | CIO 308 2.17 | CIO 308 2.17 |
| | \bigcirc | Translated | CIO 308 2.20 | CIO 308 2.20 | CIO 308 2.20 | CIO 308 2.20 | CIO 308 2.20 |



INFO

To avoid confusion, it is recommended not to change the unit in the translation for the AGC 200.